# SIMING FAN

# Personal Page(simon3dv.github.io)

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## EDUCATION

University of Electronic Science and Technology of China(UESTC)08.2017 - Presentbachelor in Informational and Computing Science(Direction of Computer Science)Sichuan,ChinaSchool of Mathematical SciencesWeighted Average Mark:88.13(rank 4/37)

## RESEARCH

LIDAR/RGB-LIDAR 3D Object Detection	11.2018 - 11.2019
Research on raw-point based method(frustum-pointnets, frustum-convnet as	nd PointRCNN), instead
of BEV-based and voxel-based method. Besides, research on embeding RG	B information into point
cloud feature(PointFusion, DenseFusion, PointPainting, ImVoteNet). Use K	itti 3D Object Detection
Benchmark for evaluation.	
First, reproduce PointNet in Pytorch, including pre-prossessing and visulizat	ion, which are not open-

First, reproduce PointNet in Pytorch, including pre-prossessing and visulization, which are not opensource.(Blog)

Second, first person to reproduce frustum-pointnets in Pytorch(not include RGB Detector), 10+ stars now.(simon3dv/frustum-pointnets-pytorch)

Third, reproduce DenseFusion in frustum-convnet, improving accuracy from 85 to 86 in Kitti validation dataset(caronly, Moderate).(simon3dv/frustum-convnet )

LIDAR Unsupervised Domain Adaptive 3D Object Detection 11.2019 - Present Supervised by Professor Mao Ye. In 2020.03, I created a domain adaptation dataset via existing dataset(Kitti to nuScenes). Now I am Using frustum-convnet and PointRCNN as baseline, and trying adversial-based and reconstruction-base method. Part of my code is in simon3dv/frustum-pointnetspytorch while others are private for the time being.

#### TECHNICAL STRENGTHS

$\mathbf{C}$	3-year
Python	2-year
Pytorch	1-year
Matlab	1-year
Ubuntu	2-year
$\mathbf{English}$	CET6 excellent $(565)$

# EXTRA-CIRRUCULAR

Third Prize in 2019 UESTC Mathematical Modeling Contest Third Prize in 2018 UESTC Programming Contest Final Third Prize in 2019 UESTC ACM Contest

#### SCHOLARSHIP

Excellent Student Scholarship(10% of the participants)